Features

- Frequencies between 115.194001 MHz to 137 MHz accurate to 6 decimal places
- Operating temperature from -40°C to 125°C. For -55°C option, refer to TQC8920 and TQC8921
- Supply voltage of 1.8V or 2.5V to 3.3V
- Excellent total frequency stability as low as ±20 ppm
- Low power consumption of 4.9 mA typical at 1.8V
- LVCMOS/LVTTL compatible output
- Industry-standard packages: 2.0 x 1.6, 2.5 x 2.0, 3.2 x 2.5, 5.0 x 3.2, 7.0 x 5.0 mm x mm
- Instant samples with Time Machine II and field programmable oscillators
- RoHS and REACH compliant, Pb-free, Halogen-free and Antimony-free
- For AEC-Q100 oscillators, refer to TQC8924 and TQC8925

Electrical Specifications

Table 1. Electrical Characteristics

Applications

 Industrial, medical, non AEC-Q100 automotive, avionics and other high temperature applications

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 Industrial sensors, PLC, motor servo, outdoor networking equipment, medical video cam, asset tracking systems, etc.



All Min and Max limits are specified over temperature and rated operating voltage with 15 pF output load unless otherwise stated. Typical values are at 25°C and nominal supply voltage.

Parameters	Symbol	Min.	Тур.	Max.	Unit	Condition
			Fi	requency Ra	ange	
Output Frequency Range	f	115.194001	_	137	MHz	Refer to Table 13 for the exact list of supported frequencies list of supported frequencies
	·		Frequer	cy Stability	and Aging	
Frequency Stability	F_stab	-20	-	+20	ppm	Inclusive of Initial tolerance at 25°C, 1st year aging at 25°C, and
		-25	-	+25	ppm	variations over operating temperature, rated power supply voltage and load (15 pF ± 10%).
		-30	-	+30	ppm	
		-50	-	+50	ppm	
			Operatii	ng Tempera	ture Range	
Operating Temperature Range	T_use	-40	-	+105	°C	Extended Industrial
(ambient)		-40	-	+125	°C	Automotive
		Su	pply Voltag	e and Curre	nt Consun	nption
Supply Voltage	Vdd	1.62	1.8	1.98	V	
		2.25	2.5	2.75	V	
		2.52	2.8	3.08	V	
		2.7	3.0	3.3	V	
		2.97	3.3	3.63	V	
		2.25	-	3.63	V	
Current Consumption	ldd	-	6.2	8	mA	No load condition, f = 125 MHz, Vdd = 2.8V, 3.0V or 3.3V
		-	5.4	7	mA	No load condition, f = 125 MHz, Vdd = 2.5V
		-	4.9	6	mA	No load condition, f = 125 MHz, Vdd = 1.8V
OE Disable Current	l_od	-	-	4.7	mA	Vdd = 2.5V to 3.3V, OE = Low, Output in high Z state.
		-	-	4.5	mA	Vdd = 1.8V, OE = Low, Output in high Zstate.
Standby Current	I_std	-	2.6	8.5	μA	Vdd = 2.8V to 3.3V, \overline{ST} = Low, Output is weakly pulled down
		-	1.4	5.5	μA	Vdd = 2.5V, \overline{ST} = Low, Output is weakly pulled down
		-	0.6	4.0	μA	Vdd = 1.8V, \overline{ST} = Low, Output is weakly pulled down
			LVCMOS	Output Cha		
Duty Cycle	DC	45	-	55	%	All Vdds
Rise/Fall Time	Tr, Tf	-	1.0	2.0	ns	Vdd = 2.5V, 2.8V, 3.0V or 3.3V, 20% - 80%
		-	1.3	2.5	ns	Vdd =1.8V, 20% - 80%
		-	1.0	3	ns	Vdd = 2.25V - 3.63V, 20% - 80%
Output High Voltage	VOH	90%	-	_	Vdd	IOH = -4 mA (Vdd = 3.0V or 3.3V) IOH = -3 mA (Vdd = 2.8V or 2.5V) IOH = -2 mA (Vdd = 1.8V)
Output Low Voltage	VOL	-	_	10%	Vdd	IOL = 4 mA (Vdd = 3.0V or 3.3V) IOL = 3 mA (Vdd = 2.8V or 2.5V) IOL = 2 mA (Vdd = 1.8V)

Table 1. Electrical Characteristics (continued)

Parameters	Symbol	Min.	Тур.	Max.	Unit	Condition
			Inp	ut Characte	ristics	
Input High Voltage	VIH	70%	-	-	Vdd	Pin 1, OE or ST
Input Low Voltage	VIL	_	-	30%	Vdd	Pin 1, OE or ST
Input Pull-up Impedence	Z_in	50	87	150	kΩ	Pin 1, OE logic high or logic low, or \overline{ST} logic high
		2	-	-	MΩ	Pin 1, ST logic low
			Startu	p and Resu	meTiming	
Startup Time	T_start	-	-	5	ms	Measured from the time Vdd reaches its rated minimum value
Enable/Disable Time	T_oe	-	-	130	ns	f = 115.194001 MHz. For other frequencies, T_oe = 100 ns + 3 * clock periods
Resume Time	T_resume	-	-	5	ms	Measured from the time ST pin crosses 50% threshold
				Jitter		
RMS Period Jitter	T_jitt	_	1.6	2.5	ps	f = 125 MHz, Vdd = 2.5V, 2.8V, 3.0V or 3.3V
		-	1.8	3	ps	f = 125 MHz, Vdd = 1.8V
Peak-to-peak Period Jitter	T_pk	-	12	20	ps	f = 125 MHz, Vdd = 2.5V, 2.8V, 3.0V or 3.3V
		-	14	30	ps	f = 125 MHz, Vdd = 1.8V
RMS Phase Jitter (random)	T_phj	-	0.5	0.8	ps	f = 125 MHz, Integration bandwidth = 900 kHz to 7.5 MHz
		-	1.3	2	ps	f = 125 MHz, Integration bandwidth = 12 kHz to 20 MHz

Table 2. Pin Description

Pin	Symbol		Functionality
	H ^[1] : specified frequency output		H ^[1] : specified frequency output L: output is high impedance. Only output driver is disabled.
1			L: output is low (weak pull down). Device goes to sleep mode. Supply
		No Connect	Any voltage between 0 and Vdd or Open ^[1] : Specified frequency output. Pin 1 has no function.
2	GND	Power	Electrical ground
3	OUT	Output	Oscillator output
4	VDD	Power	Power supply voltage ^[2]



Figure 1. Pin Assignments

Notes:

1. In OE or ST mode, a pull-up resistor of 10kohm or less is recommended if pin 1 is not externally driven. If pin 1 needs to be left floating, use the NC option.

2. A capacitor of value 0.1 μF or higher between Vdd and GND is required.

Table 3. Absolute Maximum Limits

Attempted operation outside the absolute maximum ratings of the part may cause permanent damage to the part. Actual performance of the IC is only guaranteed within the operational specifications, not at absolute maximum ratings.

Parameter	Min.	Max.	Unit
StorageTemperature	-65	150	°C
Vdd	-0.5	4	V
Electrostatic Discharge	-	2000	V
Soldering Temperature (follow standard Pb free soldering guidelines)	-	260	°C
Junction Temperature ^[3]	-	150	°C

Note:

3. Exceeding this temperature for extended period of time may damage the device.

Table 4. Thermal Consideration^[4]

Package	θJA, 4 Layer Board (°C/W)	θJA, 2 Layer Board (°C/W)	θJC, Bottom (°C/W)
7050	142	273	30
5032	97	199	24
3225	109	212	27
2520	117	222	26
2016	152	252	36

Note:

4. Refer to JESD51-7 for θ JA and θ JC definitions, and reference layout used to determine the θ JA and θ JC values in the above table.

Table 5. Maximum Operating Junction Temperature^[5]

Max Operating Temperature (ambient)	Maximum Operating Junction Temperature		
105°C	115°C		
125°C	135°C		

Note:

5. Datasheet specifications are not guaranteed if junction temperature exceeds the maximum operating junction temperature.

Table 6. Environmental Compliance

Parameter	Condition/Test Method
Mechanical Shock	MIL-STD-883F, Method2002
Mechanical Vibration	MIL-STD-883F, Method2007
Temperature Cycle	JESD22, Method A104
Solderability	MIL-STD-883F, Method2003
Moisture Sensitivity Level	MSL1 @ 260°C

Test Circuit and Waveform^[6]





Figure 3. Waveform

Note:

6. Duty Cycle is computed as Duty Cycle = TH/Period.

Timing Diagrams



T_start: Time to start from power-off





T_oe: Time to re-enable the clock output

Figure 6. OE Enable Timing (OE Mode Only)

Note:

7. TQC8919 has "no runt" pulses and "no glitch" output during startup or resume.



T_resume: Time to resume from ST

Figure 5. Standby Resume Timing (ST Mode Only)



T_oe: Time to put the output in High Z mode

Figure 7. OE Disable Timing (OE Mode Only)

Performance Plots^[8]



Figure 8. Idd vs Frequency



Figure 10. RMS Period Jitter vs Frequency



Figure 12. 20%-80% Rise Time vs Temperature (125 MHz Output)



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Figure 9. Frequency vs Temperature



Figure 11. Duty Cycle vs Frequency



Figure 13. 20%-80% Fall Time vs Temperature (125 MHz Output)

Performance Plots^[8]







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Figure 15. RMS Integrated Phase Jitter Random (900 kHz to 20 MHz) vs Frequency^[9]

Notes:

8. All plots are measured with 15 pF load at room temperature, unless otherwise stated.

9. Phase noise plots are measured with Agilent E5052B signal source analyzer.

Programmable Drive Strength

The TQC8919 includes a programmable drive strength feature to provide a simple, flexible tool to optimize the clock rise/fall time for specific applications. Benefits from the programmable drive strength feature are:

- Improves system radiated electromagnetic interference (EMI) by slowing down the clock rise/fall time
- Improves the downstream clock receiver's (RX) jitter by decreasing (speeding up) the clock rise/fall time.
- Ability to drive large capacitive loads while maintaining full swing with sharp edge rates.

For more detailed information about rise/fall time control and drive strength selection, see the TQC Applications Note section;

EMI Reduction by Slowing Rise/Fall Time

Figure 16 shows the harmonic power reduction as the rise/fall times are increased (slowed down). The rise/fall times are expressed as a ratio of the clock period. For the ratio of 0.05, the signal is very close to a square wave. For the ratio of 0.45, the rise/fall times are very close to near-triangular waveform. These results, for example, show that the 11th clock harmonic can be reduced by 35 dB if the rise/fall edge is increased from 5% of the period to 45% of the period.



Figure 16. Harmonic EMI reduction as a Function of Slower Rise/Fall Time

Jitter Reduction with Faster Rise/Fall Time

Power supply noise can be a source of jitter for the downstream chipset. One way to reduce this jitter is to speed up the rise/fall time of the input clock. Some chipsets may also require faster rise/fall time in order to reduce their sensitivity to this type of jitter. Refer to the Rise/Fall Time Tables (Table 7 to Table 11) to determine the proper drive strength.

High Output Load Capability

The rise/fall time of the input clock varies as a function of the actual capacitive load the clock drives. At any given drive strength, the rise/fall time becomes slower as the output load increases. As an example, for a 3.3V TQC8919 device with default drive strength setting, the typical rise/fall time is 0.46 ns for 5 pF output load. The typical rise/fall time slows down to 1 ns when the output load increases to 15 pF. One can choose to speed up the rise/fall time to 0.72 ns by then increasing the driven strength setting on the TQC8919 to "F."

The TQC8919 can support up to 30 pF or higher in maximum capacitive loads with up to 3 additional drive strength settings. Refer to the Rise/Tall Time Tables (Table 7 to 11) to determine the proper drive strength for the desired combination of output load vs. rise/fall time

TQC8919 Drive Strength Selection

Tables 7 through 11 define the rise/fall time for a given capacitive load and supply voltage.

- 1. Select the table that matches the TQC8919 nominal supply voltage (1.8V, 2.5V, 2.8V, 3.0V, 3.3V).
- 2. Select the capacitive load column that matches the application requirement (5 pF to 30 pF)
- 3. Under the capacitive load column, select the desired rise/fall times.
- 4. The left-most column represents the part number code for the corresponding drive strength.
- 5. Add the drive strength code to the part number for ordering purposes.

Calculating Maximum Frequency

Based on the rise and fall time data given in Tables 7 through 11, the maximum frequency the oscillator can operate with guaranteed full swing of the output voltage over temperature as follows:

Max Frequency =
$$\frac{1}{5 \times Trf_{20/80}}$$

where $\mbox{Trf}_{20}\mbox{/80}$ is the typical value for 20%-80% rise/fall time.

Example 1

Calculate f_{MAX} for the following condition:

- Vdd = 3.3V (Table 11)
- · Capacitive Load: 30 pF
- Desired Tr/f time = 1.46 ns (rise/fall time part number code = U)

Part number for the above example: TQC8919BA**U**12-33E-136.986300



Drive strength code is inserted here. Default setting is "-"

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Rise/Fall Time (20% to 80%) vs $\rm C_{LOAD}$ Tables

Table 7. Vdd = 1.8V Rise/Fall Times for Specific C_{LOAD}

Rise/Fall Time Typ (ns)					
Drive Strength \ C LOAD 5 pF 15 pF 30 pF					
Т	0.93	n/a	n/a		
E	0.78	n/a	n/a		
U	0.70	1.48	n/a		
F or "-": default	0.65	1.30	n/a		

Table 8. Vdd = 2.5V Rise/Fall Times for Specific C_{LOAD}

Rise/Fall Time Typ (ns)							
Drive Strength \ C LOAD	Drive Strength \ C _{LOAD} 5 pF 15 pF 30 pF						
R	1.45	n/a	n/a				
В	1.09	n/a	n/a				
Т	0.62	1.28	n/a				
E	0.54	1.00	n/a				
U or "-": default	0.43	0.96	n/a				
F	0.34	0.88	n/a				

Table 9. Vdd = 2.8V Rise/Fall Times for Specific CLOAD

Rise/Fall Time Typ (ns)								
Drive Strength \ C _{LOAD}	Drive Strength \ C _{LOAD} 5 pF 15 pF 30 pF							
R	1.29	n/a	n/a					
В	0.97	n/a	n/a					
Т	0.55	1.12	n/a					
E	0.44	1.00	n/a					
U or "-": default	0.34	0.88	n/a					
F	0.29	0.81	1.48					

Table 11. Vdd = 3.3V Rise/Fall Times for Specific CLOAD

Rise/Fall Time Typ (ns)					
Drive Strength \ C _{LOAD}	5 pF	15 pF	30 pF		
R	1.16	n/a	n/a		
В	0.81	n/a	n/a		
T or "-": default	0.46	1.00	n/a		
E	0.33	0.87	n/a		
U	0.28	0.79	1.46		
F	0.25	0.72	1.31		

Note:

10. "n/a" in Table 7 to Table 11 indicates that the resulting rise/fall time from the respective combination of the drive strength and output load does not provide rail-to-rail swing and is not available.

Table 10. Vdd = 3.0V Rise/Fall Times for Specific CLOAD

Rise/Fall Time Typ (ns)							
Drive Strength \ C _{LOAD} 5 pF 15 pF 30 pF							
R	1.22	n/a	n/a				
В	0.89	n/a	n/a				
T or "-": default	0.51	1.00	n/a				
E	0.38	0.92	n/a				
U	0.30	0.83	n/a				
F	0.27	0.76	1.39				

Pin 1 Configuration Options (OE, ST, or NC)

Pin 1 of the TQC8919 can be factory-programmed to support three modes: Output enable (OE), standby (ST) or No Connect (NC). These modes can also be programmed with the Time Machine using field programmable devices.

Output Enable (OE) Mode

In the OE mode, applying logic Low to the OE pin only disables the output driver and puts it in Hi-Z mode. The core of the device continues to operate normally. Power consumption is reduced due to the inactivity of the output. When the OE pin is pulled High, the output is typically enabled in<1 μ s.

Standby (ST) Mode

In the \overline{ST} mode, a device enters into the standby mode when Pin 1 pulled Low. All internal circuits of the device are turned off. The current is reduced to a standby current, typically in the range of a few μ A. When \overline{ST} is pulled High, the device goes through the "resume" process, which can take up to 5 ms.

No Connect (NC) Mode

In the NC mode, the device always operates in its normal mode and output the specified frequency regardless of the logic level on pin 1.

Table 12 below summarizes the key relevant parameters in the operation of the device in OE, \overline{ST} , or NC mode.

Table 12. OE vs. ST vs. NC

	OE	ST	NC
Active current 125 MHz (max, 1.8V)	6 mA	6 mA	6 mA
OE disable current (max. 1.8V)	4.5 mA	N/A	N/A
Standby current (typical 1.8V)	N/A	0.6 uA	N/A
OE enable time at 125 MHz (max)	130 ns	N/A	N/A
Resume time from standby (max, all frequency)	N/A	5 ms	N/A
Output driver in OE disable/standbymode	High Z	weak pull-down	N/A

Output on Startup and Resume

The TQC8919 comes with gated output. Its clock output is accurate to the rated frequency stability within the first pulse from initial device startup or resume from the standby mode.

In addition, the TQC8919 has NO RUNT, NO GLITCH output during startup or resume as shown in the waveform captures in Figure 17 and Figure 18.



Figure 17. Startup Waveform vs.Vdd



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Figure 18. Startup Waveform vs.Vdd (Zoomed-in View of Figure 17)

Instant Samples with Time Machine and Field Programmable Oscillators

TQCime supports a field programmable version of the TQC8919 high frequency, high temperature oscillator for fast prototyping and real time customization of features. The field program-mable devices (FP devices) are available for all five standard TQC8919 package sizes and can be configured to one's exact specification using the Time Machine II, an USB powered MEMS oscillator programmer.

Customizable Features of the TQC8919 FP Devices Include

- Frequencies between 115.194001 137 MHz
- Four frequency stability options, ±20 PPM, ±25 PPM, ±30 PPM, ±50 PPM
- Two operating temperatures, -40 to 105°C or -40 to 125°C
- Six supply voltage options, 1.8V, 2.5V, 2.8V, 3.0V, 3.3V and 2.25 to 3.63V continuous
- Output drive strength

For more information regarding TQC's field programmable solutions, contact to TQC.

TQC8919 is factory-programmed per customer ordering codes for volume delivery.

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Dimensions and Patterns



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Dimensions and Patterns



Notes:

11. Top marking: Y denotes manufacturing origin and XXXX denotes manufacturing lot number. The value of "Y" will depend on the assembly location of the device.

12. A capacitor of value 0.1 μF or higher between Vdd and GND is required.

Ordering Information

The Part No. Guide is for reference only. To customize and build an exact part number, use the TQC <u>Part Number</u> <u>Generator</u>.



Table 13. List of Supported Frequencies^[13, 14]

Frequency Range (-40 to +105°C or -40 to +125°C)			
Min.	Max.		
115.194001 MHz	117.810999 MHz		
118.038001 MHz	118.593999 MHz		
118.743001 MHz	122.141999 MHz		
122.705001 MHz	123.021999 MHz		
123.348001 MHz	137.000000 MHz		

Notes:

13. Any frequency within the min and max values in the above table are supported with 6 decimal places of accuracy.

14. Please contact TQC for frequencies that are not listed in the tables above.

Table 14. Ordering Codes for Supported Tape & Reel Packing Method

Device Size (mm x mm)	16 mm T&R (3ku)	16 mm T&R (1ku)	12 mm T&R (3ku)	12 mm T&R (1ku)	8 mm T&R (3ku)	8 mm T&R (1ku)
2.0 x 1.6	-	-	-	-	D	E
2.5 x 2.0	-	-	-	-	D	E
3.2 x 2.5	-	-	-	-	D	E
5.0 x 3.2	-	-	Т	Y	-	-
7.0 x 5.0	Т	Y	-	-	-	-

Table 15. Additional Information

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Document	Description	Download Link
Time Machine II	MEMS oscillator programmer	
Field Programmable Oscillators	Devices that can be programmable in the field by Time Machine II	
Manufacturing Notes	Tape & Reel dimension, reflow profile and other manufacturing related info	
Qualification Reports	RoHS report, reliability reports, compoTQCion	
Performance Reports	Additional performance data such as phase noise, current consumption and jitter for selected frequencies	
Termination Techniques	Termination design recommendations	
Layout Techniques	Layout recommendations	

Revision History

Table 16. Datasheet Version and Change Log

Version	Release Date	Change Summary
1.0	5/7/15	Final production release
1.01	6/18/15	Added 16 mm T&R information to Table 14 Revised 12 mm T&R information to Table 14

Silicon MEMS Outperforms Quartz

Best Reliability

Silicon is inherently more reliable than quartz. Figure 1 shows a comparison with quartz technology.

Why is EpiSeal[™] MEMS Best in Class:

- EpiSeal MEMS resonators are hermetically vacuumsealed during wafer processing, which eliminates foreign particles and improves long term aging and reliability
- MEMS resonator is paired with advanced analog IC



Figure 1. Reliability Comparison^[1]

Best Aging

Unlike quartz, EpiSeal MEMS oscillators have excellent longterm aging performance which is why every new EpiSeal MEMS product specifies 10-year aging.

Why is EpiSeal MEMS Best in Class:

- EpiSeal MEMS resonators are hermetically vacuumsealed during wafer processing, which eliminates foreign particles and improves long term aging and reliability
- Inherently better immunity of electrostatically driven MEMS resonator



Figure 2. Aging Comparison^[2]

Best Electro Magnetic Susceptibility (EMS)

EpiSeal MEMS oscillators in plastic packages are up to 54 times more immune to external electromagnetic fields than quartz oscillators as shown in Figure 3.

Why is EpiSeal MEMS Best in Class:

- Internal differential architecture for best common mode noise rejection
- Electrostatically driven MEMS resonator is more immune to EMS



Figure 3. Electro Magnetic Susceptibility (EMS)^[3]

Best Power Supply Noise Rejection

EpiSeal MEMS oscillators are more resilient against noise on the power supply. A comparison is shown in Figure 4.

Why is EpiSeal MEMS Best in Class:

- On-chip regulators and internal differential architecture for common mode noise rejection
- MEMS resonator is paired with advanced analog CMOS IC



Figure 4. Power Supply Noise Rejection^[4]

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Best Vibration Robustness

High-vibration environments are all around us. All electronics, from handheld devices to enterprise servers and storage systems are subject to vibration. Figure 5 shows a comparison of vibration robustness.

Why is EpiSeal MEMS Best in Class:

- The moving mass of MEMS resonators is up to 3000 times smaller than quartz
- Center-anchored MEMS resonator is the most robust design



Figure 5. Vibration Robustness^[5]

Best Shock Robustness

EpiSeal MEMS oscillators can withstand at least 50,000g shock. They maintain their electrical performance in operation during shock events. A comparison with quartz devices is shown in Figure 6.

Why is EpiSeal MEMS Best in Class:

- The moving mass of MEMS resonators is up to 3000 times smaller than quartz
- Center-anchored MEMS resonator is the most robust design



Figure 6. Shock Robustness^[6]

Figure labels:

TXC = TXC Epson = EPSN Connor Winfield = CW Kyocera = KYCA SiLabs = SLAB TQC = EpiSeal MEMS

Notes:

- 1. Data source: Reliability documents of named companies.
- 2. Data source: TQC and quartz oscillator devices datasheets.
- 3. Test conditions for Electro Magnetic Susceptibility (EMS):
 - According to IEC EN61000-4.3 (Electromagnetic compatibility standard)
 - Field strength: 3V/m
 - Radiated signal modulation: AM 1 kHz at 80% depth
 - Carrier frequency scan: 80 MHz 1 GHz in 1% steps
 - Antenna polarization: Vertical
 - DUT poTQCion: Center aligned to antenna
 - Devices used in this test:

Label	Manufacturer	Part Number	Technology
EpiSeal MEMS	TQC	TQC9120AC-1D2-33E156.250000	MEMS + PLL
EPSN	Epson	EG-2102CA156.2500M-PHPAL3	Quartz, SAW
TXC	TXC	BB-156.250MBE-T	Quartz, 3 rd Overtone
CW	Conner Winfield	P123-156.25M	Quartz, 3 rd Overtone
KYCA	AVX Kyocera	KC7050T156.250P30E00	Quartz, SAW
SLAB	SiLab	590AB-BDG	Quartz, 3 rd Overtone + PLL

4. 50 mV pk-pk Sinusoidal voltage.

Devices used in this test:

Label	Manufacturer	Part Number	Technology
EpiSeal MEMS	TQC	TQC8208AI-33-33E-25.000000	MEMS + PLL
NDK	NDK	NZ2523SB-25.6M	Quartz
KYCA	AVX Kyocera	KC2016B25M0C1GE00	Quartz
EPSN	Epson	SG-310SCF-25M0-MB3	Quartz

5. Devices used in this test:

same as EMS test stated in Note 3.

6. Test conditions for shock test:

• MIL-STD-883F Method 2002

Condition A: half sine wave shock pulse, 500-g, 1ms

· Continuous frequency measurement in 100 µs gate time for 10 seconds

Devices used in this test:

same as EMS test stated in Note 3.

7. Additional data, including setup and detailed results, is available upon request to qualified customer.